## Automatic Gate Openers

International registered trademark n. 804888

## SWING 2 DG

## SWING 2 DG R2F <br> SWING 2 DG R2BF

## CONTROL UNIT <br> TO MANAGE ONE OP TWO OPERATORS <br> (230V/110V)

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## PRELIMINARY

The SWING 2 DG control unit requires the programming of the working times (chapter 15); it is not possible to start the operator correctly without first programming the control unit!

- The unit and the accessories programming and settings can be carried out by the display on board or by the JOLLY 3 programmer or SEACLOUD
- Functions and menus here described are valid only for the below listed software revisions; if some functions or menus do not correspond to your control unit, consult the previous manuals MODEL SOFTWARE REVISION

MAIN DIFFERENCES BETWEEN THE TWO VERSIONS
Management of normal n.C. photocells only. - Standard N.C. or balanced 8K2 safety edges management only
SWING 2 DG R2F
03.05
$\longrightarrow$
also management of two 10K photocells. - Also management of a 8 K2 pure resistive safety edge powered; only after completing all wirings the control unit can be switched on and programmed

## TECHNICAL INFORMATION

| POWER SUPPLY | ABSORPTION <br> IN STAND-BY | OPERATING <br> TEMPERATURE | PROTECTION CLASS <br> OF THE PLASIC BOX <br> (IF INCLUDED) |
| :---: | :---: | :---: | :---: |
| $230 \mathrm{VAC}-50 / 60 \mathrm{~Hz}$ | 30 mA | $-20^{\circ} \mathrm{C}$ |  |
| OR | $+50^{\circ} \mathrm{C}$ |  |  |
| $115 \mathrm{VAC}-50 / 60 \mathrm{~Hz}$ |  |  | IP 55 |

## RESET PROCEDURE



## QUICK START

- Make all connections (control unit OFF!): motors, accessories and power cables
- DO NOT jumper the N.C. contacts! - automatic detection of the N.C. contacts not in use!
- Power on the control unit and check the correct status of the inputs (chapter 14)
- Enter the basic menu and set the following menus: (if you do not set a time on menu 7, the logic will be

| 1 |
| :---: | :---: |
| LANGUAGE |

GATES
NUMBER
6
LOGIC

$\stackrel{7}{\text { TIMER }}$ TO CLOSE «semi-automatic» - automatic reclosing disabled)

- Move the operator using the menus

| MO2 |
| :---: |
| MOVE |
| GATE 1 |

$\qquad$ ; if the gate opens by pressing if the gate closes by pressing ${\underset{\text { DOWN }}{0}}_{\circ}^{\circ}$, the motors run correctly, otherwise swap the motors cables - If installed, enable the encoder or the potentiometer on menu 32 - paragraph 15.2

- Start up the working times learning by following the procedure in chapter 15


## 1 - WIRINGS

Make all the wirings when the control unit is not powered!
Keep the power cables separate from the command cables - always run cables in separate sheaths to prevent interferences!



[^0]
## 2-CONNECTIONS ON CN1

## 2.1 - START (N.O.)

Connect the «START» command on clamps 9 and 14 (15/16)
Logics to be linked to the «START» command in chapter 16 $\Rightarrow$ If the input is engaged during the pause time, the gate does not close until the input is released

## 2.2 - PARTIAL START (N.O.)

- Connect the «PARTIAL START» on clamps 10 and 14 (15/16)
- Logics to be linked to the «START» command in chapter 16
- Partial opening space management:

| 90 <br> PRRTAL <br> OPENING |
| :---: |
| 91 <br> PARTAL <br> PAUSE |

$\Rightarrow$ If the input is engaged during the pause time, the gate does not close until the input is released
$i$ If a TRAFFIC LIGHT is wired via SEM 2 unit, it is possible to enable the entry or exit priority linked to the «START» or «PARTIAL START» commands, via menu 89


## 2.3 - TIMER (N.O.) - EXTERNAL CLOCK

Connect the timer to the clamp 10 «PARTIAL START» or to the clamp 13 «PHOTOCELL 2»

- If wired to the «PARTIAL START», this command will be disabled (on transmitters too)
- The timer opens and keeps the gate open until engaged; when released, the gate closes only after the pre-set pause time has elapsed
- In the event of a safety accessory intervention, the timer automatically resets after 6 sec . $\Rightarrow$ In the event of a power failure when the gate is open:
if the TIMER is still active when the power is restored, the gate remains open; if the TIMER is no longer active, a «START» input will be required to close the gate


## 2.4 - STOP (N.C.)

Connect the button for the «STOP» command on the clamps 11 and 14 (or 15 or 16) - After the «STOP» command, press «START» to restore the movement (the operator always starts-up in closing after the «STOP» command!)

## 2.5 - PHOTOCELL 1 AND PHOTOCELL 2 (N.C.)

- Wirings:

$$
+=24 \mathrm{~V}=\max 500 \mathrm{~mA} \text { (clamp 17) } \quad C O M=0 \mathrm{~V} \text { (clamps 14-15-16) PHOTOCELLS! }
$$

PH1 = Photocell 1 (clamp 12) PH2 = Photocell 2 (clamp 13)

- Management and photocells operating settings: menu 97 (photo 1) and menu 98 (photo 2)
$\Rightarrow$ Default settings of the menus: 97 = «CLOSING»; 98 = «OPENING AND CLOSING»
- «РнототеST» function: connect the Tx-photocell negative cable on the clamp 19 «TEST»


## 2.6-10K PHOTOCELL SINGLE OR DOUBLE OK PHOTOCELLS - onLy on MOdEL «SWING 2 DG R2BF»

- Connect 10K photocells on clamps 12-14-17 and 13-14-17 $\Rightarrow$ Also use the two «COM» inputs on clamps 15 or 16 instead of the clamp 14

One or two 10K photocells can be connected;
set the menus 121 or 122 to «Рното 1 10к» or «Рното $210 \mathrm{~K} »$


EXAMPLE OF 10K PHOTOCELLS CONNECTION


121314151617


97

- The desired operation mode can be set on the menus «РнотосеLL» 97 and 98 $\Rightarrow$ By the use of the 10 K photocells, a further protection is given, even in the event of a shortcircuit on the cables!


## 2.7- LATCH OPENING OR LATCH CLOSING BUTTON

Connect the button to use as LATCH on clamps 10 and 14

A.
The PARtiAL Start function will be disabled!


- Management: set the desired operation mode on the menu 118
- To release the LATCH, press again the same button used to enable the function $\Rightarrow$ The LATCH command can also be sent from SEACLOUD or enabled on the second channel of the transmitter (paragraph 18.4), thus keeping the PARTIAL START input free;



## 2.8 - EXTERNAL RECEIVER

- An external receiver can be connected according to the connection diagram on the side.

For the operation of the receiver, refer to its instruction manual


## 2.9-24V =- DC AUX OUTPUT OPTIONS - Clamp 18-max 500mA

- Management: on menu 94 choose how to have voltage on the AUX output, according to the type of accessory you have wired


Connect the accessory only after setting the menu 94 on the desired option!

- A relay can be connected to the 24VAUX output; the relay allows the connection and the management of additional accessories (locks etc.); some examples below, including the menu 94 settings

MAGNETIC LOCK - BY THE USE OF TWO DIFFERENT RELAY MODELS

- To use the magnetic lock, set the menu 94 to «negative BRAKE MANAGEMENT" (24Vaux output powered during the cycle and 1 second before starting up)



## VERTICAL LOCK - bY THE USE OF TWO DIFFERENT RELAY MODELS

- To use the vertical lock, set the menu 94 to «NegAtive BRAKE MANAGEMENT" (24Vaux output powered during the cycle and 1 second before starting up)



## 3- CONNECTION ON CN2

## 3.1 - MOTOR CONNECTION ON THE CONTROL UNIT


$\Rightarrow$ In the case of a single leaf, connect the operator as motor 1; if necessary, adjust the menus parameters for M1 only

## 3.2 - COURTESY LIGHT



』
Max. 50W $\rightarrow 230 \mathrm{~V}$ Max. $100 \mathrm{~W} \rightarrow 115 \mathrm{~V}$

Wire the courtesy light as shown in the diagram

- Courtesy light operation can be managed by menu 88

i) If the courtesy light is wired via SEM 2 management unit (paragraph 9.1), then it is possible to set the timing from 1 to 240 seconds, on the menu 88



## 4 - POWER SUPPLY CONNECTION ON CN3

## 4.1-CONTROL UNIT POWER SUPPLY



- FUSE 16AT DELAYED ON 230V~ POWER SUPPLY Fuse 16AT DeLAYED ON 115V~ POWER SUPPLY
- Use a 10A differential switch to protect the power supply system
- In case of unstable power supply, the use of an external UPS of min. 800 VA is recommended


For the connection to the power grid respect the laws in force

## 5 - CONNECTION ON CN4

## 5.1-12V ELECTRIC LOCK



## 5.2-24V FLASHING LIGHT

- Connect the $24 \mathrm{~V}=$ flashing light as shown in the diagram
- The flashing light send signals when the gate moves: 1 blink/SECOND IN OPENING


2 blinks/second in closing Steady lit during pause

86
FLASHING
LIGHT

- Management of the operating mode: menu 86
- Pre-flashing function management: menu 85

85
FLASHING
$\Rightarrow$ The control unit sends the warning signals also through the flashing lamp; see chapter 19 «ALARMs»

## 5.3-24V BUZZER



Connect the 24 V =- oscillating Buzzer as shown in the diagram

- The Buzzer can be connected instead of the flashing light; it is necessary to set the menu 86 to «BUZZER»

- The Buzzer activates after 2 consecutive interventions of the anti-crushing protection
$\Rightarrow$ Press the STOP button to turn off the buzzer; anyway, the sound switches off automatically after 5 minutes and the operator remains stopped waiting for a new command


## 6 - CONNECTION ON CN5

| 6.1 - SAFETY EDGE (N.C.) |  |  |  |
| :---: | :---: | :---: | :---: |
| CN5 | - Choice of the safety edges type - MENU 100 |  | $\begin{aligned} & \mathbf{1 0 0} \\ & \text { SAFETY } \\ & \text { EDGE } \end{aligned}$ |
| $\begin{array}{\|l\|l\|l\|l\|l\|l\|} \hline 2223 \end{array}$ | - Choice of the desired direction - MENU 102 (103*) | (102 | (103** |

SAFETY EDGE $i$ A second safety edge (N.C. normnal type) can be connected to the «PHOTOCELL 2» input and can be enabled by setting the menu 98 to «SAFETY EDGE 2»


## * The direction of this second safety edge can be managed by the menu 103

$\Rightarrow$ Options: 8K2 baLANCED SAFETY EDGE or 8 K2 RESISTIVE SAFETY EDGE:
It is possible to wire an 8K2 bALANCED SAFETY EDGE or a PURE 8 K 2 RESISTIVE SAFETY EDGE (only on R2BF version) to control the contact through a resistance value to detect any short-circuits (in case of shortcircuit, an alarm will be displayed - see chapter 19)


On model «R2F»: MANAGEMENT OF A SINGLE 8K2 bALANCED SAFETY EDGE (N.c.)


ON MODEL 《R2BF»: MANAGEMENT OF A SINGLE 8K2 bALANCED SAFETY EDGE (N.C.) OR OF A SINGLE 8K2 PURE RESISTIVE SAFETY EDGE

## 7-CONNECTION ON CN6

## 7.1- LIMIT SWITCH - on «FC» VERSION ONLY




Wire the opening and closing limit switches of the first and the second operator as shown in the diagram $\Rightarrow$ The type of limit switch is automatically detected during the working times learning

## ANTI-INTRUSION FUNCTION:

This function is linked to the limit switch activation; if enabled via the menu 79 , this function restores the original position of the gate after a manual forcing or a blast of wind

## 8 - CONNECTION ON CN7 and CN8

## 8.1 - ANTENNA

Connect the antenna on the CN7 terminal according to the wiring diagram

## 8.2 - DRY CONTACT RELAY

A
Dry contact relay available only on hardware version $« R 2$ DRY CONTACT» with additional relay
CN8 - dry contact relay: max. 3A and 250V

- The relay is for general use, for example it is possible to connect a timer to turn on a light
- Default operation in «START 3s» mode: the relay automatically activates at each «START» or «PARTIAL START» impulse for 3 seconds or at each photocell intervention

- On «R2BF» model it is possible to disable the «START 3s» operation by the menu 132 and choose to activate the relay manually, via remote control (by storing the relay activation function on a TX key - see paragraph 18.4)



## 9-CONNECTION ON EXP

## 9.1 - «SEM 2» MANAGEMENT UNIT



> The SEM 2 accessories management unit allows you to connect and manage the following additional accessories:
> - TRAFFIC LIGHT
> - COURTESY LIGHT
> - VERTICAL ELECTRIC LOCK
> - POSITIVE OR NEGATIVE ELECTRIC BRAKE
$\Rightarrow$ SEM2 READS THE LIMIT SWITCHES STATUS (to connect those accessories whose activation depends on the limit switches status)
(i) More details on SEM 2 instructions

## 9.2 - «LSE» or «LE» or «LRT» MANAGEMENT UNITS



The LSE (or LE) or LRT management circuits allow you to connect and manage different additional accessories, such as additional limit-switches, the temperature probe, the POTENTIOMETER or the RT ENCODER
(1) More details on LSE/LE/LRT instructions

## 9.3 - «POSITION GATE» LINEAR POTENTIOMETER CONNECTION VIA «LSE» or «LE»

P01/P02 = BLUE
D1/D2 = BLACK P11/P12 = BROWN


Connect the «POSITION GATE» linear potentiometer for managing the correct position of the gate and the inversion on obstacles, as shown aside

Respect the cable colors
Set both the DS1 DIP-SWITCHES to «OFF»


DIP SWITCH 1 = OFF DIP SWITCH $2=0$ FF
$\Rightarrow$ The use of 3-pole shielded cables IS MANDATORY! - WIRE THE SHIELDS ON P11 AND P12

- To enable the linear potentiometer:

1 The menus 51-52-53 (54-55-56) will be visible only if the potentiometer is enabled; the menus allow pulses to be displayed and adjusted - paragraph 9.5

## 9.4 - «RT»ABSOLUTE ENCODER CONNECTION VIA «LRT» CIRCUIT



Connect the «RT» ABSOLUTE ENCODER for managing the correct position of the gate and the inversion on obstacles, as shown aside

- Respect the cable colors

Set both the DS1 DIP-SWITCHES to «OFF»


DIP SWITCH 1 = OFF DIP SWITCH 2 = OFF
$\Rightarrow$ The use of 3-pole shielded cables is MANDATORY! - WIRE THE SHIELDS ON P11 AND P12

To enable the «RT» ENCODER


1. The menus 51-52-53 (54-55-56) will be visible only if the «RT» ENCODER is enabled; the menus allow pulses to be displayed and adjusted - paragraph 9.5

The Anti-intrusion function is also available; It is linked to the potentiometer or the «RT» encoder activation; If enabled via menu 79, this function restores the original
 position of the gate after a manual forcing or a blast of wind

## 9.5 - LINEAR POTENTIOMETER or «RT» ABSOLUTE ENCODER CONFIGURATION

$\Rightarrow$ The menus 51-52-53-54-55-56 are visible only when the menu 32 is set to «POSITION GATE» or ENCODER «RT»

- Motor 1 (menu 51) or motor 2 (menu 54) partial impulses; display of the operator current position


Motor 1 (menu 52) or motor 2 (menu 55) impulses in opening; display of the impulses when the leaf is completely open; possibility to increase or decrease the total pulses


- Motor 1 (menu 53) or motor 2 (menu 56) impulses in closing; display of the impulses when the leaf is completely closed; possibility to increase or decrease the total pulses



## 9.6 - POTENTIOMETER or «RT» ENCODER PARAMETERS ADJUSTMENT

- Sensitivity parameters in opening and closing (Motor 1 and Motor 2) for potentiometer intervention time adjustment
$\Rightarrow$ For a quick reverse on obstacle decrease the sensitivity

i.

Set to OFF (intervention excluded): merely detection of the impulses (does not reverse on obstacle)

- Slowdown sensitivity menu to adjust the inversion time during the slow down
$\Rightarrow$ For a quick reverse on obstacle
decrease the sensitivity

- To adjust the Encoder intervention threshold values in opening and closing (Motor 1 and Motor 2)
$\Rightarrow$ The lower the threshold, the greater the force required for the inversion

- To adjust the threshold values for the Encoder intervention during the slow down, in opening and closing (Motor 1 and Motor 2)
$\Rightarrow$ The lower the threshold, the greater the force required for the inversion



## 9.7 - ACCESS TO THE HIDDEN «DEBUG» MENU

- Display of the instantaneous speed values detected «VP1» and «VP2» (motor 1 and motor 2) to adjust the thresholds above described (thresholds must always be lower than the values shown in VP1 or VP2)



## 10 - RECEIVER CONNECTIONS



Respect the plug-in direction of the different circuits; RF FIX: the «ANT» contacts printed on the receiver circuit and control unit circuit must match $R X$ module: the «24V» «COM» and «START» contacts on the receiver and control unit must match

| SEA PLUG-IN RECEIVERS | MAX. USERS NUMBER |
| :---: | :---: |
| RF UNI | 16 USERS WITHOUT ADDITIONAL MEMORY 800 USERS With MEMO ADDitional MEMORY |
| RF UNI PG (Old Model - non extractable memory) | 100 USERS IF PROGRAMMED IN FIX Code <br> 800 USERS If programmed in Rolling Code Plus |
| RF UNI PG (New Model - extractable memory) | 496 USERS IF programmed in Fix Code <br> 800 USERS If programmed in Rolling Code Plus |
| RF FIX | 16 USERS WITHOUT ADDITIONAL MEMORY 100 USERS With MEMO additional memory |

## 11-ADDITIONAL FUNCTIONS

## 11.1- «I/O SURGE PROTECTOR» CIRCUIT



OUTPUT
CONNECTION ON CONTROL UNIT 24V DC ACCESSORIES CONTACT 1 (Es. PHOTOCELL) CONTACT 2 (Es. SAFETY EDGE) CONTACT 3 (Es. START) CONTACT 4 CONTACT 5 CONTACT 6

INPUT
ACCESSORIES CONNECTION

## 24V DC ACCESSORIES

CONTACT 1 (Es. PHOTOCELL)
CONTACT 2 (Es. SAFETY EDGE)
CONTACT 3 (Es. START)
CONTACT 4
CONTACT 5
CONTACT 6

- To protect up to 6 inputs and the 24 V power supply from temporary overloads (ie. lightning strikes)
- Connect the 24 VDC cable and the accessories cables on INPUT; connect the corresponding cables from OUTPUT to the control unit


## 12 - DISPLAY and PROGRAMMING

CONNECT ALL THE ACCESSORIES WHEN THE CONTROL UNIT IS SWITCHED OFF! AFTER ALL CONNECTIONS HAVE BEEN MADE, POWER ON THE UNIT FOR SETTINGS
12.1 - DISPLAY DETAILS - ref. chapter 14

## STANDARD DISPLAY



In standard display the inputs are represented by OFF or ON dashes depending on whether the corresponding contact respectively is OPEN or CLOSED

## DISPLAY «BINGO» OPTIONAL ONLY FOR «R2BF»

In the new bingo display the inputs are represented by «0» and «1» symbols depending on whether the corresponding contact is OPEN (0) or CLOSED (1)

All other screens and views are identical in the two displays
12.2 - POWER ON THE CONTROL UNIT


## 12.3 - BASIC MENU and SPECIAL MENU

The control unit has a BASIC MENU (chapter 13) which allows the basic settings in order to start using the product quickly

- The SPECIAL MENU allows to change default settings, or to enable/disable the accessories or the control unit functions
- To access the SPECIAL MENU use one of the two following methods

$\Rightarrow$ In the BASIC MENU it is possible to select the operator type in use and other necessary options. Once the type has been chosen, all the special menus are automatically set to the default values useful for that operator, so further settings may not be necessary


## 13 - BASIC MENU



## 14 - INPUTS STATUS MANAGEMENT

## 14.1 - INPUTS DISPLAY



## 14.2 - INPUTS DISPLAY ON «BINGO»

- Every input corresponds to a fixed position on the display, according to the diagram below
- Every input can be: normally open (0) - normally closed (1)
0 N.O. - NORMALLY OPEN
1
N.C. - Normally closed

| 1 2 3 4 5 6 7 8 <br> 4 4 4 4 4 4 4 4 | 2 | START (*) PARTIAL START | $\left[\begin{array}{c}9 \\ 10\end{array}\right.$ | MOTOR 1 OPENING LIMIT SWITCH <br> MOTOR 1 CLOSING LIMIT SWITCH |
| :---: | :---: | :---: | :---: | :---: |
|  | 3 | STOP | 11 | MOTOR 2 OPENING LIMIT SWITCH |
| 00111110 | 4 | PHOTOCELL 1 | 12 | MOTOR 2 CLOSING LIMIT SWITCH |
| 11110000 | 5 | PHOTOCELL 2 | 13 | NOT IN USE |
|  | 6 | SAFETY EDGE 1 | 14 | NOT IN USE |
| $\downarrow \downarrow \downarrow \downarrow$ | 7 | SAFETY EDGE 2 | 15 | NOT IN USE |
| 910111213141516 | 8 | NOT IN USE | 16 | NOT IN USE |

* If a TIMER is connected to the START input, it keeps the contact normally closed; in this case the display will show «T" on position $n^{\circ} 1$
- Example: if you give a «START» command, its input switches from normally open to normally closed

Example: if you pass by the photocell, its input switches from normally closed to normally open

14.3 －ACCESS TO THE INPUTS MANAGEMENT MENU
GO ON ANY
BASIC MENU NUMBER
LANGUAGE
－Inside the «INPUTS MANAGEMENT MENU» it is possible to enable or disable the inputs；paragraph 14.4
－START and PARTIAL START are NORMALLY OPEN（N．O．）contacts If «ON» is displayed when the contact is activated，then the input works If «OFF» is displayed when the contact is activated，then check the wirings

－ALL OTHER CONTACTS are NORMALLY CLOSED（N．C．）contacts If «OFF» is displayed when an accessory is wired，then the input works If «ON» is displayed when an accessory is wired，then check the wirings

$\Rightarrow$ The LIMIT SWITCHES inputs cannot be managed，but only displayed in their current state （ON OR OFF）

## 14.4 －INPUTS MANAGEMENT MENU



## 15 - WORKING TIMES LEARNING

## DANGER!

Have a qualified service person to carry out the operations in safe conditions
$\Rightarrow$ Check the correct operation of all accessories (photocells, buttons, etc.)
$\Rightarrow$ Do not jumper the inputs not in use (limit switch, safety edge, etc.)

## 15.1 - PRELIMINARY SETTINGS

$\Rightarrow$ Before programming the working times, it is necessary to carry out the essential settings of the basic menu. It is not possible to correctly start-up the times learning without carrying-on the following settings!


## 15.2 - ENCODER OR POTENTIOMETER ACTIVATION (IF INSTALLED)

- If the operator is equipped with an encoder or potentiometer (POSITION GATE), then it is necessary to check that they are correctly enabled in special menu 32, before the working times learning!



## 15.3- WORKING TIMES LEARNING BY LIMIT SWITCH

Working times learning through automatic detection of the limit switches

- Check that the special menu 32 is «OFF» (see paragraph 15.2)
- Check on the INPUTS STATUS MENU (chapter 14) that the correct limit switch is engaged for each movement direction

Start-up the working times learning by following the procedure below:

$\Rightarrow$ If the motor starts closing, reaches the limit switch lever and stops, then swap the limit switch cables and repeat the procedure;
$\Rightarrow$ If the motor starts opening, reaches the limit switch lever and stops, then swap the motor cables and repeat the procedure;

## 15.4 - WORKING TIMES LEARNING BY POTENTIOMETER or «RT» ENCODER

FOR «RT» ENCODER: USE this PROCEDURE ONLY ON SWING GATE OPERATORS!

- Working times learning through the automatic detection of the end-of-stroke points
- Enable the «POSItion GATE» or «RT» ENCODER in special menu 32 (see paragraph 15.2)
- Start-up the working times learning by following the procedure below:


THE LEARNING CYCLE STARTS: M2 CLOSES
 In case the «РОTENTIOMETER DIRECTION» alarm is displayed, swap the brown wire with the blue wire and repeat the times learning - VALID ONLY FOR LINEAR POTENTIOMETER!

| After the learning, it is possible to check the correct reading of the impulses by accessing the following menus (paragraph 9.5): | $\begin{gathered} 52 \\ \text { I. AP.M1 } \end{gathered}$ | $\begin{gathered} 53 \\ \text { I.CH.M1 } \end{gathered}$ | $\begin{gathered} 54 \\ \text { I. PAR. M2 } \end{gathered}$ | $\begin{gathered} 55 \\ \text { I. AP. M2 } \end{gathered}$ | $\begin{gathered} 56 \\ \text { 1. CH. M2 } \end{gathered}$ |
| :---: | :---: | :---: | :---: | :---: | :---: |
| After the learning, it is possible to adjust the sensitivity parameters by the following menus (paragraph 9.6): | $\begin{array}{\|c\|} \hline 33 \\ \hline \text { M1 OPENNG } \\ \text { SENSITVITYY } \end{array}$ | $\begin{gathered} 34 \\ \text { M1 COSNG } \\ \text { SNSSITIVTTY } \end{gathered}$ | $\begin{gathered} 35 \\ \begin{array}{c} \text { M2 OPENNG } \\ \text { SNSITIVITY } \end{array} \end{gathered}$ | $\begin{array}{\|c\|} \mathbf{3 6} \\ \text { M2CLOSNG } \\ \text { SNNSITIVTTY } \end{array}$ |  |

## 15.5 - WORKING TIMES LEARNING BY MANUAL PULSES

i
For operators without limit switch, without encoder and without potentiometer (I.E: DOUBLE SWING GATE OPERATORS)

- Times learning through manual pulses on the points of stop
- Check that the menu 32 is «OFF» (see paragraph 15.2); if necessary, manually adjust the working times by the menus: (these menus are available only when the menu 32 is «OFF»)


68
M2 CLOSING TIME


MANUAL PULSES ON STOP POINTS
$\Rightarrow$ If the operators perform the first learning cycle starting in opening, wait for the end of the cycle and reverse the motors rotation through the menu 5, then repeat the learning procedure


## 15.6 - LEARNING BY MANUAL PULSES - with POTENTIOMETER or «RT» ENCODER

Times learning through POTENTIOMETER or «RT» ENCODER which detect the manual pulses on the desired points of stop (allowing the choice of the end-of-stroke points)

- Enable the POTENTIOMETER OR «RT» ENCODER on menu 32 (paragraph 15.2)

$\Rightarrow$ If the operators perform the first learning cycle starting in opening, wait for the end of the cycle and reverse the motors rotation through the menu 5, then repeat the learning procedure


1In case the «POTENTIOMETER DIRECTION» alarm is displayed, swap the brown wire with the blue wire and repeat the times learning - VALID ONLY FOR LINEAR POTENTIOMETER!

- After the learning, it is possible to check the correct reading of the impulses by accessing the

| 51 |
| :---: |
| I. PAR. M1 |


| 52 |
| :---: |
| I. AP. M1 |


| 53 |
| :---: |
| I. CH. M1 |


| 54 |
| :---: |
| I. PAR. M2 |



56
I. CH. M2 following menus (paragraph 9.5):

- After the learning, it is possible to adjust the sensitivity parameters by the following menus (paragraph 9.6):

| 33 |
| :---: |
| M1 OPENNG |
| SENSITVITY |


| 34 |
| :---: |
| M1 CLOSING |
| SENSITIVITY |



## 16-LOGICS

The default logic is «automatic», anyway it Can be changed after the working times learning!
SEMI-AUTOMATIC LOGIC: automatically set when the menu 7 is «OFF» (automatic reclosing disabled)


- SEMI-AUTOMATIC operation: a START command opens the gate; another START command closes; In semi-automatic logic, the automatic reclosing is always disabled.
- This logic matches with other logics (except «AUTOMATIC»), keeping the automatic reclosing disabled
- AUTOMATIC LOGIC: pre-set by default. Anyway it can be manually enabled through the menu 6 or through the menu 7 by setting a pause time different than 0 and up to 240 seconds (The menu 7 also enables the automatic reclosing when different than 0)

- Through the menu 8 it is possible to choose if the START command given during the pause time is accepted or not


AUTOMATIC operation: a START command opens the gate; another START command is not accepted if given during the opening; a START command reverses the movement if given during the closing

SAFETY LOGIC: a START command opens the gate; another START command reverses the movement if given during the opening a START command reverses the movement if given during the closing

STEP BY STEP TYPE 1 LOGIC: the START command follows the logic: OPEN -STOP -CLOSE -STOP -OPEN


STEP BY STEP TYPE 2 LOGIC: the START command follows the logic: OPEN -STOP - CLOSE - OPEN


DEAD MAN LOGIC: the gate opens as long as the START command is held pressed; when released the gate stops. The gate closes as long as the PARTIAL START is held pressed; when released
 the gate stops.
$\underline{2}$ BUTTONS LOGIC: a START command opens the gate; a PARTIAL START command closes the gate


The START command reopens the gate if given during the closing. The PARTIAL START command is not accepted if given during the opening or during the closing

## 17 - PASSWORD

- Once the password is enabled, all the menus can not be adjusted, they are only displayed - If you forget the password, contact the SEA technical assistance: SEA reserves the right to evaluate and decide whether to provide or not the unlocking procedure



## 18 - RECEIVERS AND TRANSMITTERS

Connect the receiver circuit when the control unit is not powered, as shown in chapter 10

When the control unit is switched-off, check if the receiver is correctly plugged in

- Program the transmitters before connecting the antenna
- Program the transmitters only when the gate is closed and the motor is stopped
- RF UNI and RF UNI PG allow the use of both roll plus/UNI TX and FIX code tX
- RF FIX allows the use of FIX CODE transmitters only
- It is possible to store up to 2 among the available functions
- The START command must ALWAYS be stored on the first channel of the TX
- If the second stored function is modified, then all the transmitters acquire this change on the second channel
$\Rightarrow$ The first stored transmitter determines the coding of the following ones if the first transmitter is stored as ROLLING CODE, then all the followings must be stored as ROLLING CODE; transmitters with different coding are not accepted - see the coding passage on Tx instruction!


## 18.1- OLD «ROLLING CODE» CODING



More details on the functions available in paragraph 18.4
18.2-«ROLLING CODE PLUS» - «UNI» - «FIX CODE» TRANSMITTERS

$\Rightarrow$ More details on the functions available in paragraph 18.4

## 18.3 - «START» COMMAND QUICK LEARNING

## 18.4 - TRANSMITTERS FUNCTIONS DIAGRAM



## 19 - ALARMS

## 19.1 - FAULTS SHOWN ON THE DISPLAY

- The control unit advises of the faults may happen through a message on the display (Note: press ok to exit the message)

- Below the list of the faults that are signaled on the display and the possible solutions to the problems (ifthe fault message holds out, contact the technical support)

| WARNING MESSAGE | SOLUTION |
| :---: | :---: |
| FAULT MOTOR | Motor power supply fault - Check that there are no short circuits on the motor or on the control unit; check that the gate is not blocked or stuck on a stop point. Check that the encoder (if enabled) is correctly wired to the control unit. Unlock the operator and give a START command to check that the motor runs: if the motor runs then disconnect the power supply, lock the operator again and restore the power supply; ifthe motor does not run, then it is burned |
| FAULT 24 | 24 V or 24 VAUX power supply fault - Check that there are no short circuits on wirings or on the control unit; check that there is no overload |
| FAULT NET | Main power supply fault - Check that a power failure is not occurred; check that the main power supply is active; Check the fuse F2 |
| FAULT PHOTOCELL 1 SELF-TEST | «РнотосеLL 1 SELF-TEST» function fault - Check the operation of the photocells and/or their wirings on the control unit |
| FAULT PHOTOCELL 2 SELF-TEST | «РнотосеLL 2 SELF-TEST» function fault - Check the operation of the photocells and/or their wirings on the control unit |
| FAULT LIMIT SWITCH | Limit switch activation fault - Check the operation of both limit switches and that there is a correspondence between the direction of movement of the motor and the limit switch engaged |
| FAULT POTENTIOMETER (1 or 2) | Potentiometer fault - The message appears only if the menu 32 is set to «POSITION GATE». The potentiometer management unit (LE / LSE) is damaged or not correctly wired or set |
| FAULT POTENTIOMETER DIRECTION (M1) | Potentiometer cables wiring error on Motor 1-Swap the wiring cables of the potentiometer (swap the blue cable with the brown cable) |
| FAULT POTENTIOMETER DIRECTION (M2) | Potentiometer cables wiring error on Motor 2 - Swap the wiring cables of the potentiometer (swap the blue cable with the brown cable) |
| FAULT POTENTIOMETER «RT» OR POSITION GATE | Potentiometer fault - The message appears only if the menu 32 is set to «POSITION GATE» or to «RT》. The potentiometer management unit (LE/LSE) or the «RT» encoder management unit (LRT) is damaged or not correctly wired or set |
| FAULT FLASHING LIGHT | Flashing light fault - Check the wirings and / or the condition of the lamp |
| FAULT <br> SAFETY EDGE (1 or 2) | Safety edge fault - Check the metal wire of the safety edge and the cables wirings. Check that the contact is closed by accessing the «INPUT STATUS» menu (paragraph 14.2) |
| FAULT ENCODER | Encoder fault - The message appears only if the menu 32-ENCODER is set to «ON». The Encoder management unit (LE / LSE) is damaged or not correctly wired or set |
| PASSWORD ERROR | Password error - Enter the password correctly; It is not possible to set «0000» as a password; If you forgot the password, please contact the technical assistance. |

## 19.2 - FAULTS SIGNALED ON THE FLASHING LIGHT

- It is also possible to visualize the warning signals through the flashing light simply by observing the number of flashes emitted (see the table of correspondences below)
- When an event occurs, the warning flashes will be issued at each «START» command

| ALARM TYPE | NUMBER OF FLASHES |
| :---: | :---: |
| Motor fallure (M1 or M2) | 9 SLOW (EVERY 0.5 SEC) 10 TIMES |
| Photocell fallure during closing | 2 SLOW (EVERY 0.5 SEC) 5 TIMES |
| Photocell failure during opening | 3 SLOW (EVERY 0.5 SEC) 5 TIMES |
| Photocell self-test failed | 3 SLOW (EVERY 0.5 SEC$) 1$ time |
| Collision - ObStacle detected during opening | 6 SLOW (EVERY 0.5 SEC) 10 TIMES |
| COLLISION - OBSTACLE DETECTED DURING CLOSING | 6 SLOW (EVERY 0.5 SEC) 10 TIMES |
| Safety edge fallure | 4 SLOW (EVERY 0.5 SEC) 3 TIMES |
| M1 POTENTIOMETER FAILURE | 11 fast (EVERY 0.2 SEC$) 4$ TIMES |
| M2 POTENTIOMETER FAILURE | 11 FAST (EVERY 0.2 SEC$) 4$ TIMES |
| «RT»》 POTENTIOMETER OR «POSITION GATE» FAULT | 11 FAST (EVERY 0.2 SEC$) 4$ TIMES |
| Fault on Stop contact | 5 SLOW (EVERY 0.5 SEC$) 1$ time |
| LIMIT SWITCH FAILURE OR ERROR | 4 FAST (EVERY 0.2 SEC$) 10$ TIMES |
| Max. CYCLES ACHIEVED-MAINTENANCE REQUIRED | 7 SLOW (EVERY 0.5 SEC) 1 TIME |

The «CYCLES ALARM» warning refers to the reaching of the maximum cycles number established after which the maintenance is necessary

## 19.3 - «DIAGNOSTICS» MENU TO DISPLAY LATEST EVENTS

- The warnings and the alarms remain in the control unit memory, up to a max. of 10 events. To see the stored events, access the menu 106. Below is the table with the type of events saved in the diagnostics

$\Rightarrow$ If the fault message holds out, carry out the required checks or disconnect the device generating the fault

| TYPE OF EVENT | WARNING MESSAGE STORED |
| :---: | :---: |
| EvENTS OR ALARMS REGARDING FAULTS ON MOTOR | MOTOR FAULT |
| Events or alarms regarding faults on photocell 1 OR Photocell 2 In opening | PHOTO OPENING |
| Events or alarms regarding faults on photocell 1 OR Photocell 2 In CLosing | PHOTO CLOSING |
| Events or alarms regarding faults on 10K photocells | 10K PHOTOCELL |
| Events or alarms regarding the detection of obstacles in the opening phase | OBSTACLE IN OPENING |
| Events or alarms concerning the detection of obstacles in the closing phase | OBSTACLE IN CLOSING |
| Events or alarms concerning faults on the safety edge 1 | SAFETY EDGE 1 FAULT |
| Events or alarms concerning faults on the safety edge 2 | SAFETY EDGE 2 FAULT |
| Events or alarms concerning faults on the absolute potentiometer | POT. 1 or POT. 2 FAULT |
| Events or alarms concerning fault on the «STOP» CONTACT | STOP |
| Reaching of the maximum cycles established - maintenance required | MAINTENANCE |
| Events or alarms concerning faults on the main power supply | MISSING NETWORK |
| Events or alarms concerning faults on the opening or closing limit switches | LIMIT SWITCH |

$\mathbb{1}$
It IS always recommended to consult the chapter 20 dedicated to troubleshooting. Most of the problems can be solved by following the given instructions!

## 20-TROUBLESHOOTING

## Make sure that all the safety devices are «ON»

| PROBLEM | POSSIBLE REASON | SOLUTION |
| :---: | :---: | :---: |
| The operator does not respond to any START command | a) Check that the N.C. are connected <br> b) Blown fuse | a) Check the connections and the jumpers on the safety edge or stop or photocell inputs, if connected <br> b) Replace the blown fuse on the control unit |
| The operator does not run and the diagnostic display is off | a) The control unit is not powered <br> b) Fuse open <br> c) Defective control unit | a) Check the AC power supply <br> b) Check the fuses <br> c) Replace the defective control unit |
| The operator does not respond to a wired command (example: Opening, Closing, etc.) | a) Check the inputs of the opening and closing commands <br> b) The STOP button is activated <br> c) The Reset button is blocked <br> d) Anti-entrapment safety device active | a) Check all the opening and closing inputs to make sure they are not blocked <br> b) Check the STOP button is not blocked <br> c) Check the Reset button <br> d) Check among all the inputs of the anti-entrapment protection device, if there is a blocked sensor |
| The operator does not respond to a remote control | a) The STOP button is activated <br> b) The Reset button is blocked <br> c) Poor radio reception | a) Check the STOP button is not blocked <br> b) Check the Reset button <br> c) Check if the other wired devices are working correctly; check the antenna cable |
| The motor runs in one direction only | a) Check the resistance between the motor phase and neutral and verify that the resistance is MOhm <br> b) Try to invert the motor phase and see if it changes direction or not | a) Replace the cable <br> b) If the motor is blocked, replace the cable; if the motor moves in one direction only, the motor direction relay is damaged |
| The gate does not move but the motor runs | a) The engine is in the locked position <br> b) Presence of an obstacle | a) Release the motor <br> b) Remove the obstacle |
| The gate does not reach the complete open or closed position | a) Wrong limit switch setting <br> b) Programming error <br> c) Gate is stopped by an obstacle <br> d) Torque too low <br> e) The gate is too heavy to perform the automatic slowdown | a) Set the limit switches <br> b) Repeat the working times programming <br> c) Remove the obstacle <br> d) Increase the torque parameter <br> e) Set the slowdown to OFF |
| The gate opens but does not close | a) The photocells contacts are connected and open <br> b) Stop contact connected and open <br> c) The safety edge contact is open <br> d) Amperometric alarm | a) b) c) Check the jumpers or the connected devices or the warning signals on the flashing lamp <br> d) Check for a possible the amperometric alarm and, if necessary, increase the torque parameter |
| The gate does not close automatically | a) Pause time set too high <br> b) Semi-automatic logic control unit | a) Adjust the pause time <br> b) Set the PAUSE TIME menu to a value different than OFF |
| The gate moves, but the limit switches cannot be set correctly | a) The gate does not move towards a stop position <br> b) It is too difficult to move the gate | a) Manually unlock and move the gate and make sure the gate moves easily from limit switch to limit switch. <br> If necessary, repair the gate <br> b) The gate must be able to move easily and freely throughout its travel, from limit switch to limit switch. <br> If necessary, repair the gate |
| The gate does not fully open or close when the limit switches are set | a) The gate does not move towards a limit switch <br> b) It is too difficult to move the gate | a) Manually unlock and move the gate and make sure the gate moves easily from limit switch to limit switch. <br> If necessary, repair the gate <br> b) The gate must be able to move easily and freely throughout its travel, from limit switch to limit switch. <br> If necessary, repair the gate |
| The gate stops during travel and reverses direction | a) Open/Close control active <br> b) The obstacle detection sensitivity is too low | a) Check if there is an active input among all the opening and closing inputs <br> b) Check the obstacle detection sensitivity value and try to increase it |
| The gate opens but does not close with TX or closing timer | a) Opening control active <br> b) Pause not set <br> c) The closing anti-entrapment protection device is active <br> d) The photocell contact is open <br> e) The fire switch input is active | a) Check if there is an active input among the open inputs <br> b) Check the pause settings <br> c) Check if there is an active sensor among all the inputs of the antientrapment protection device <br> d) Check the contact of the photocells <br> e) Check the fire switch input |


| PROBLEM | POSSIBLE REASON | SOLUTION |
| :---: | :---: | :---: |
| The gate does not respect the slowdown start points | a) The encoder does not work properly when activated <br> b) Slow mechanical clutch <br> c) Too large deceleration space <br> d) The potentiometer does not work correctly when activated <br> e) The parameters of the recovery position are too high or too low | a) Check in the Encoder menu that the "Encoder Par" parameter is set from a low value of $+/-\mathbf{1 0}$ (gate completely closed) to "Encoder tot" (gate completely open). If the IPAR movement is not in line with the range of values (from $+/-10$ to "Encoder tot") probably the encoder is defective <br> b) Tighten the mechanical clutch <br> c) Reduce the slowdown space <br> d) Check in the Potentiometer menu that the "IPAR" parameter is set from "I.CH." (gate completely closed) to "I.AP." (gate completely open). If the"IPAR" movement is not in line with the range of values (from I.AP. to I.CH.), the potentiometer is probably faulty <br> e) Reduce or increase the values of the "recovery position" |
| The gate opens suddenly but any START command have been given | a) Frequency or disturbances on the main line <br> b) Short-circuit on the START contact | a) The $A C$ wiring must be separated from the $D C$ wires and run through separate conduits. If it is a frequency disturbance, you can change the frequency to another MHz value, such as 868 or FM <br> b) Check all the START contacts |
| The gate does not accept the close command during the pause in automatic logic, even if the loop or photocell are set as Start | a) START IN PAUSE is not ON <br> b) The photocell/loop input is not set as "pause reload" | a) Turn ON the START IN PAUSE menu <br> b) Set "pause reload" in the photocell / loop menu |
| The gate does not have the necessary force to close or reach the limit switch | a) Slowing down is not possible either because the gate is too heavy or because of the inclination or because the installation is not new | a) Set the slowdown to OFF |
| The gate travel is obstructed and cannot stop or reverse | a) Force the necessary adjustment | a) Refer to the adjustment parameter to carry out the obstruction tests and make the correct adjustments of the force (sensitivity torque) |
| The photocell does not stop or reverse the gate travel | a) The photocell wiring is incorrect <br> b) The photocell is faulty <br> c) The photocells have been installed too far apart | a) Check the photocell wiring. Check that the gate stops and reverses its direction when the photocell is engaged <br> b) Replace the faulty photocell. Check that the gate stops and reverses its direction when the photocell is engaged <br> c) Install the photocells closer or use safety edges with sensors |
| The safety edge does not stop or reverse the travel of the gate | a) Incorrect wiring of the edge sensor <br> b) Defective edge sensor | a) Check the safety edge wiring. Check that the gate stops and reverses its direction when the edge is activated <br> b) Replace the defective safety edge and check that the gate stops and reverses its direction when it is activated |
| The alarm sounds for 5 minutes or the alarm sounds after a command | a) A double entrapment has occurred (two obstructions within a single activation) | a) Check the cause of the entrapment detection (obstruction) and correct it. Press the reset button to silence the alarm and reset the operator |
| The shadow loop does not hold the gate on the opening limit switch | a) Shadow loop sensor incorrectly adjusted <br> b) Defective shadow loop sensor <br> c) Wrong setting | a) Check the shadow loop settings and reset as needed <br> b) Replace the defective vehicle sensor <br> c) Check that menu 98 is on SHADOW LOOP |
| The accessories connected to the accessory power supply do not work properly, they turn off or restart | a) Accessory power supply protection active <br> b) Defective electronic control unit | a) Disconnect all devices powered by the "accessories power supply" and measure their voltage (must be $\mathbf{2 3 - 3 0} \mathrm{Vdc}$ ). If the voltage is correct, reconnect the accessories one at a time, measuring each time the voltage <br> b) Replace the defective control unit |
| Fault on the 24VAUX | a) Overload/short-circuit on AUX input <br> b) Blown fuse | a) Check if the cable is shorted <br> b) Replace the fuse |
| The control unit turns on but the motor does not run | a) STOP active or wrong jumpers <br> b) Open or close the active input <br> c) Active Entrapment Protection Device <br> d) Defective electronic control unit | a) Check that the STOP button is not blocked, that it is a N.C. contact or put a jumper on the Stop input <br> b) Check that none of the opening and closing inputs are blocked <br> c) Check whether there is a blocked sensor among all the entrapment protection device inputs <br> d) Replace the defective control unit |

THE DESCRIBED FUNCTIONS ARE VALID FOR ALL SWING 2 DG VERSIONS, EXCEPT WHERE EXPRESSLY STATED


| MENU |  | SET | DESCRIPTION | Defauti | NOTE |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 7 | TIMER TO CLOSE | Off | Semi-automatic logic enabled a START command opens and another START closes the gate - automatic reclosing disabled | Off |  |
|  |  | 240 | To set a pause time (from 1 second to 4 minutes) before the automatic reclosing |  |  |
| 8 | START IN PAUSE | Off | The START command is not accepted during pause | Off |  |
|  |  | On | The START command is accepted during pause |  |  |
| 9 | PROGRAMMING | Off On | To start up the working times learning | Off |  |
| 10 | TEST START | Off On | To give a START command for testing the operator (This command can be used only if the unit has already been programmed!) | Off |  |
| 13 | LATCH PAUSE | Off On | If «ON» the operator complies with the pause time set when the function «LATCH OPENING» is disabled. When «OFF» the pause time set is not respected | Off |  |
| 14 | RESET | A count-down of 5 seconds will start by holding the UP button; at its end «INIT» will appear on the display as confirmation of the control board reset |  |  |  |
| 192 | MOVE GATE 1 * | Allows to move the gate in order to test the motor running or simply to position the gate as desired. The command works in a temporary «dead man» mode: <br> HOLD UP PRESSED = THE GATE OPENS <br> HOLD DOWN PRESSED = THE GATE CLOSES |  | --- |  |
| 193 | MOVE GATE 2 * | Allows to move the gate in order to test the motor running or simply to position the gate as desired. The command works in a temporary «dead man» mode: <br> HOLD UP PRESSED = THE GATE OPENS <br> HOLD DOWN PRESSED = THE GATE CLOSES |  | ---- |  |

* The command is accepted only at the end of the cycle or after a STOP command; it is not accepted during the cycle and during the pause

| $\mathbf{1 5}$ | END | Press OK to return to the display of the firmware version <br> and to the one of inputs state |
| :--- | :--- | :---: |
| $\mathbf{1 6}$ | SPECIAL MENU | Press OK to enter the special menu |

SPECIAL MENU
PRESS AT THE SAME TIME FOR 5 SECONDS TO ENTER OR TO EXIT THE SPECIAL MENU
THE DESCRIBED FUNCTIONS ARE VALID FOR ALL SWING 2 DG VERSIONS, EXCEPT WHERE EXPRESSLY STATED

| SPECIAL MENU |  |  | SET | DESCRIPTION | DEfault | NOTE |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 26 | Leaf delay in opening | Off | 6 | Adjustable from OFF to 6 seconds | 1,5 |  |
| 27 | LEAF DELAY IN CLOSING | Off | 20 | Adjustable from OFF to $\mathbf{2 0}$ seconds | 2,5 |  |
| 28 | OPENING TORQ 1 | 30\% | 100 \% | Motor 1 torque in opening: <br> the higher the torque value, the more force is required to execute the inversion in case of obstacle. <br> The torque is set to $100 \%$ on hydraulic operators | 75\% |  |
| 29 | CLOSING TORQ 1 | 30\% | $100 \%$ | Motor 1 torque in closing: <br> the higher the torque value, the more force is required to execute the inversion in case of obstacle. <br> The torque is set to $100 \%$ on hydraulic operators | 75\% |  |
| 30 | OPENING TORQ 2 | 30\% | 100 \% | Motor 2 torque in opening: <br> the higher the torque value, the more force is required to execute the inversion in case of obstacle. <br> The torque is set to $100 \%$ on hydraulic operators | 75\% |  |
| 31 | CLOSING TORQ 2 | 30\% | $100 \%$ | Motor 2 torque in closing: <br> the higher the torque value, the more force is required to execute the inversion in case of obstacle. <br> The torque is set to $100 \%$ on hydraulic operators | 75\% |  |
| 32 | ENCODER | ON <br> (only if connected via LSE management unit) |  | ON = Standard Encoder Enabled <br> OFF = Standard Encoder Disabled <br> (when OFF, only the learnt working times are shown) | Off |  |
|  | 47 ENCODER PAR. M1 | $x x x$. |  | Impulses read by Encoder during operation (Motor 1) |  |  |
|  | 48 ENCODER TOT. M1 | $x x x$. |  | Impulses stored during programming (Motor 1) |  |  |
|  | 49 ENCODER PAR. M2 | $x x x$. |  | Impulses read by Encoder during operation (Motor 2) |  |  |
|  | 50 ENCODER TOT. M2 | $x x x$. |  | Impulses stored during programming (Motor 2) |  |  |
| 32 | ENCODER | Position Gate |  | To enable the linear potentiometer «POSITION GATE» (only if connected via LE or LSE management unit) | Off |  |
|  |  | RT |  | To enable the «RT» absolute encoder (only if connected via LRT management unit) |  |  |
|  | 51 I.PAR.M1 * |  |  | To show the current position of the potentiometer/absolute encoder on the leaf moved by Motor 1. This parameter is useful to see if the potentiometer or the absolute encoder are correctly read |  |  |
|  | 52 I.AP.M1 | From the value learned to $\pm 100$ pulses |  | To show the impulses stored by the control unit when the leaf moved by Motor 1 is fully open |  |  |
|  | 53 I.CH.M1 | From the value learned to $\pm 100$ pulses |  | To show the impulses stored by the control unit when the leaf moved by Motor 1 is fully close |  |  |
|  | 54 I.PAR.M2 * |  |  | To show the current position of the potentiometer/absolute encoder on the leaf moved by Motor 2. This parameter is useful to see if the potentiometer or the absolute encoder are correctly read |  |  |
|  | 55 I.AP.M2 | From the value learned to $\pm 100$ pulses |  | To show the impulses stored by the control unit when the leaf moved by Motor $\mathbf{2}$ is fully open |  |  |
|  | 56 I.CH.M2 | From the value learned to $\pm 100$ pulses |  | To show the impulses stored by the control unit when the leaf moved by Motor $\mathbf{2}$ is fully close |  |  |

[^1]|  | SPECIAL MENU | SET | DESCRIPTION | Defaut | NOTE |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 32 | ENCODER | OFF | ON = Standard Encoder Enabled <br> OFF = Standard Encoder Disabled <br> (when OFF, only the learnt working times are shown) | Off |  |
|  | 65 <br> 66 OPENING TIME M1 <br> 6 CLOSING TIME M1 | $x x x .5$ <br> $x x x .5$ | To display the learnt value during the working times self learning, in opening and closing (Motor 1). With UP or DOWN it is possible to increase or reduce the working times |  |  |
|  | 67 OPENING TIME M2 | $x x x .5$ $x x x .5$ | To display the learnt value during the working times self learning, in opening and closing (Motor 2). With UP or DOWN it is possible to increase or reduce the working times |  |  |
| 33 | OPENING SENSITIVITY MOTOR 1 | 10\% (Fast intervention) <br> 99\% (Slow intervention) | To adjust the Encoder or Potentiometer or «RT» Encoder intervention time on the Motor 1 in opening | Off |  |
|  |  | Off (Intervention excluded) | Disabled |  |  |
| 34 | CLOSING SENSITIVITY MOTOR 1 | 10\% (Fast intervention) <br> 99\% (Slow intervention) | To adjust the Encoder or Potentiometer or «RT» Encoder intervention time on the Motor 1 in closing | Off |  |
|  |  | Off (Intervention excluded) | Disabled |  |  |
| 35 | OPENING SENSITIVITY MOTOR 2 | 10\% (Fast intervention) <br> 99\% (Slow intervention) | To adjust the Encoder or Potentiometer or «RT» Encoder intervention time on the Motor 2 in opening | Off |  |
|  |  | Off (Intervention excluded) | Disabled |  |  |
| 36 | CLOSING SENSITIVITY MOTOR 2 | 10\% (Fast intervention) <br> 99\% (Slow intervention) | To adjust the Encoder or Potentiometer or «RT» Encoder intervention time on the Motor 2 in closing | Off |  |
|  |  | Off (Intervention excluded) | Disabled |  |  |
| 37 | sLowDown SENSITIVITY | 10\% (Fast intervention) <br> 99\% (Slow intervention) | To adjust the Encoder or Potentiometer or «RT» Encoder intervention on the Motor during the slowdown | Off |  |
|  |  | Off (Intervention excluded) | Disabled |  |  |
| 38 | M1 POTENTIOMETER THRESHOLD IN OPENING | 01000 (available only if the «Position Gate» or the «RT" Encoder have been wired and the menu 32 correctly set) | To adjust the threshold of the Potentiometer or «RT» Encoder intervention. This parameter self-determines during the working times learning but can also be adjusted later, on the condition that the set value is lower than the value shown in VP1 or VP2 (instantaneous speed values which can be shown by accessing the DEBUG menu). NOTE: The lower the threshold value, the slower is the response of the potentiometer. | $\begin{gathered} \text { lt } \\ \text { depends } \\ \text { on model } \end{gathered}$ |  |
| 39 | M1 POTENTIOMETER THRESHOLD IN CLOSING |  |  |  |  |
| 40 | M2 POTENTIOMETER THRESHOLD IN OPENING |  |  |  |  |
| 41 | M2 POTENTIOMETER THRESHOLD IN CLOSING |  |  |  |  |
| 42 | M1 POTENTIOMETER THRESHOLD IN SLOWDOWN - OPENING | $0 \quad 100$ (available only if the «Position Gate» or the «RT" Encoder have been wired and the menu 32 correctly set) | To adjust the threshold of the Potentiometer or «RT» Encoder intervention during the slowdown. <br> The value can be manually increased on the condition that the set value is lower than the value shown in VP1 or VP2 <br> (instantaneous speed values which can be shown by accessing the DEBUG menu) | It depends on model |  |
| 43 | M1 POTENTIOMETER THRESHOLD IN sLOWDOWN - Closing |  |  |  |  |
| 44 | M2 POTENTIOMETER THRESHOLD IN SLOWDOWN - OPENING |  |  |  |  |
| 45 | M2 POTENTIOMETER THRESHOLD IN SLOWDOWN - CLOSING |  |  |  |  |


| SPECIAL MENU |  |  | SET |  | DESCRIPTION | defautt |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 46 | CLOSING INVERSION <br> Not available if the menu 86 is set to «BUZZER" | Total |  |  | In case of obstacle or safety edge intervention during the closing, the gate totally reverses the movement. If the automatic reclosing is enabled (automatic logic), it is attempted for 5 times | Partial |  |
|  |  | Partial |  |  | In case of obstacle or safety edge / potentiometer / «RT» Encoder intervention, the gate partially reverses direction (of about 30 cm ) then stops |  |  |
| The menus 47-48-49-50 are shown only if the menu 32-ENCODER = ON |  |  |  |  |  |  |  |
| The menus 51-52-53-54-55-56 are shown only if the menu 32-ENCODER = Position Gate or RT |  |  |  |  |  |  |  |
| OPENING SLOWDOWN 1 |  | Off (*) 50\% Hydraulic |  |  | Adjustable from OFF (disabled) to the $50 \%$ of the stroke. On hydraulic operators, the slowdown is automatically set to «Hydraulic» if the value exceeds $\mathbf{5 0 \%}$ |  |  |
| 60 | CLOSING <br> SLOWDOWN 1 | Off (*) 50\% Hydraulic |  |  | Adjustable from OFF (disabled) to the $50 \%$ of the stroke. On hydraulic operators, the slowdown is automatically set to «Hydraulic» if the value exceeds 50\% |  |  |
| 61 | OPENING <br> SLOWDOWN 2 | Off (*) 50\% Hydraulic |  |  | Adjustable from OFF (disabled) to the $50 \%$ of the stroke. On hydraulic operators, the slowdown is automatically set to «Hydraulic» if the value exceeds $50 \%$ | $\begin{gathered} \text { It } \\ \text { depends } \\ \text { on model } \end{gathered}$ |  |
| 62 | CLOSING <br> SLOWDOWN 2 | Off (*) 50\% Hydraulic |  |  | Adjustable from OFF (disabled) to the $50 \%$ of the stroke. On hydraulic operators, the slowdown is automatically set to «Hydraulic» if the value exceeds 50\% |  |  |
| * For motors with hydraulic brake (CF) or double hydraulic brake (2CF) this parameter must be set to OFF |  |  |  |  |  |  |  |
| 63 | DECELERATION | $\begin{array}{ll} \hline 0 \% & \boxed{ } \\ \hline 100 \% & \square \\ \hline \end{array}$ |  |  | To adjust the change from normal speed to slowdown speed | 100\% |  |
| 64 | ACCELERATION | $\begin{array}{ll} \hline 0 \% & \square \\ 100 \% & \square \end{array}$ |  |  | Acceleration ramp. <br> To adjust the motor start up speed | 100\% |  |
| The menus 65-66-67-68 are shown only if the menu 32-ENCODER = OFF |  |  |  |  |  |  |  |
| 69 | ANTI OVERLAP | Off |  |  | To disable the anti-overlapping control of the leaves allowing their separate control | Off |  |
|  |  | On |  |  | To enable the anti-overlapping control of the leaves |  |  |
| 70 | OPENING POSITION RECOVERY | $\begin{array}{ll}0 & 20 \text { seconds } \\ \text { only if } & \text { 32-Encoder is OFF }\end{array}$ |  |  | After a STOP or an inversion command given during the opening, the gate recovers the excess space traveled by inertia | 1 s |  |
| 71 | CLOSING POSITION RECOVERY | $\begin{array}{lr}0 & 20 \text { seconds } \\ \text { only if } & \text { 32-Encoder is OFF }\end{array}$ |  |  | After a STOP or an inversion command given during the closing, the gate recovers the excess space traveled by inertia | 1 s |  |
| 72 | OPENING TOLERANCE MOTOR 1 |  | 100\% | (*) | To adjust the tolerance space between the recognition of the mechanical stop in opening and the recognition of the obstacle - In case of obstacle within the tolerance space, this will be considered as mechanical stop | 80\% |  |
| 73 | CLOSING TOLERANCE MOTOR 1 | 0\% | 100\% | (*) | To adjust the tolerance space between the recognition of the mechanical stop in closing and the recognition of the obstacle - In case of obstacle within the tolerance space, this will be considered as mechanical stop | 80\% |  |
| 74 | OPENING TOLERANCE MOTOR 2 |  | 100\% | (*) | To adjust the tolerance space between the recognition of the mechanical stop in opening and the recognition of the obstacle - In case of obstacle within the tolerance space, this will be considered as mechanical stop | 80\% |  |
| 75 | CLOSING TOLERANCE MOTOR 2 |  | 100\% | (*) | To adjust the tolerance space between the recognition of the mechanical stop in closing and the recognition of the obstacle - In case of obstacle within the tolerance space, this will be considered as mechanical stop | 80\% |  |
| * With «RT» Encoder: $0 \%=20$ impulses $100 \%=200$ impulses <br> With «POSITION GATE»: $0 \%=20$ impulses $100 \%=500$ impulses |  |  |  |  |  |  |  |


|  | SPECIAL MENU | SET | DESCRIPTION | DEFAULT | NOTE |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 76 | PUSHING STROKE | Time <br> Pushing Off - 3 sec <br> Stroke | Before opening, the motor starts up in closing for the time set, in order to simplify the lock release | Off |  |
|  |  | Repeat  <br> Lock Off - On <br> Release  | If $\mathbf{O N}$, the lock will be released both before and after the pushing stroke |  |  |
|  |  | End | To exit the menu |  |  |
| 77 | LOCK TIME | Off 5 seconds | To adjust the lock release time from 0 to 5 seconds | 3 s |  |
| 78 | LOCK | Only opening | To enable the lock only before opening | Openingand closing |  |
|  |  | Only closing | To enable the lock only before closing |  |  |
|  |  | Opening and closing | To enable the lock before both opening and closing |  |  |
| 79 | ANTI INTRUSION | Only opening | If the gate moves, whether due to wind or manual forcing, the function starts up the operator to restore the initial position. (function available only if limit switch or potentiometer or «RT» encoder are installed) | Off |  |
|  |  | Only closing |  |  |  |
|  |  | Opening and closing |  |  |  |
|  |  | Off |  |  |  |
| 80 | PUSHOVER | Off | The gate leaf makes an extra movement at the maximum torque to ensure the tightening of the gate In case of a STOP command, the Pushover function is restored only after a new START command | Off |  |
|  |  | Opening and closing |  |  |  |
|  |  | Only closing |  |  |  |
|  |  | Only opening |  |  |  |
| 81 | PERIODIC PUSHOVER | Off $\quad 8 h$ If the pushover is enabled | To activate the repetition of the pushover function at a time distance adjustable from 0 to 8 hours, at hourly intervals | Off |  |
| 82 | MOTOR RELEASE | Opening $1 \quad$ Off - 3 s | If different than OFF, the motor slightly reverses the rotation direction for the set time (up to 3 seconds) at the end of the cycle | Off <br> (hydraulic) <br> 0.1 <br> (mechanic) |  |
|  |  | Closing $1 \quad$ Off - 3 s |  |  |  |
|  |  | Opening 2 Off - 3 s |  |  |  |
|  |  | Closing 2 Off - 3 s |  |  |  |
|  |  | End |  |  |  |
| 83 | EXTRA TIME * | $0.0 \mathrm{~s} \quad 10 \mathrm{~s}$ | If the limit switches are installed, it is possible to add an extra time (max. 10 seconds) to the movement of the operator after the reading of the limit switches Note: If an Encoder is installed, the space can be set by impulses (from 0 to 100) | 0.0 s |  |

* Only if the operator is equipped with hydraulic slowdown and one or more slowdown-menus (from 59 to 62) are set to «HYDRAULIC» (EXTRA TIME will be applied to the operator and to the moving direction of the menu set to «HYDRAULIC»)

| 84 | BRAKE | Off | 100\% | To adjust the braking on the limit switch | Off |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 85 | PRE-FLASHING | Only closing |  | To enable the pre-flashing only before closing (To access this option: press DOWN when 0.0 is shown) | Off |
|  |  | 0.0 | 5.0 s | To set the pre-flashing duration |  |
| 86 | FLASHING LIGHT | Norm |  | Normal | Normal |
|  |  | Ligh |  | Warning lamp function |  |
|  |  | Alwa |  | Always ON |  |
|  |  | Buzz |  | Buzzer |  |
| 87 | FLASHING LIGHT AND TIMER | Off |  | The flashing light will be OFF with enabled timer and open gate | Off |
|  |  | On |  | The flashing light will be ON with enabled timer and open gate |  |
| 88 | COURTESY LIGHT | Off |  | Disabled | In cycle |
|  |  |  | 240 | Adjustable from 1 second to 4 minutes |  |
|  |  | In cy |  | Courtesy light only in cycle |  |


| SPECIAL MENU |  | SET | DESCRIPTION | DEFAULT Off | NOTE |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 89 | TRAFFIC LIGHT RESERVATION | Off On | To get the priority in entry (via a START command) or in exit (via a PARTIAL START command). The function is available only if a traffic light is wired via SEM unit |  |  |
| 90 | Partial opening | 20\% 100\% | Adjustable from $20 \%$ to $100 \%$ | 100\% |  |
| 91 | PARTIAL PAUSE | = START | The pause time in partial opening is the same as in total opening | $\begin{gathered} = \\ \text { START } \end{gathered}$ |  |
|  |  | Off | Disabled |  |  |
|  |  | 240 | Adjustable from 1 second to 4 minutes |  |  |
| 92 | TIMER | Off | The selected input will be turned into an input (on CN1) to which connect an external clock | Off |  |
|  |  | On Photocell 2 |  |  |  |
|  |  | On Partial START |  |  |  |
| 94 | 24V AUX <br> (Max. 500 mA ) <br> The AUX output allows the wiring of additional accessories via relay; accessories will work according to the chosen option | Always | AUX output always powered | Always |  |
|  |  | In cycle | AUX output powered only during cycle |  |  |
|  |  | Opening | AUX output powered only during opening |  |  |
|  |  | Closing | AUX output powered only during closing |  |  |
|  |  | In pause | AUX output powered only during pause |  |  |
|  |  | Positive brake management | AUX output powered only when the gate is stationary Ex.: positive electric brake connected via relay |  |  |
|  |  | Negative brake management | AUX output powered during cycle and 1 second before starting the movement <br> Ex.: negative electric brake connected via relay |  |  |
|  |  | Open gate warning light | 1 flash per second - during opening <br> 2 flashes per second - during closing <br> Steady lit - gate in «STOP» or «OPEN» status |  |  |
|  |  | START 3 s | AUX output powered at every START input or at every photocells or safety edge intervention, for 3 seconds <br> ie.: a courtesy light connected via relay |  |  |
| 95 | PHOTO-TEST | Photocell 1 | Self-test enabled only on photocell 1 | Off |  |
|  |  | Photocell 2 | Self-test enabled only on photocell 2 |  |  |
|  |  | Photocells 1 and 2 | Self-test enabled on photocells 1 and 2 |  |  |
|  |  | Off | Disabled |  |  |
| 97 | PHOTOCELL 1 | Closing | If the photocell is occupied during closing, the gate reverses the movement; If the photocell is occupied during the pause, it prevents the gate reclosing | Closing |  |
|  |  | Opening and closing | If the photocell is occupied during opening or closing, it stops the gate movement; when the photocell is released, the movement continues |  |  |
|  |  | STOP | If the photocell is occupied before the START input, the START will be ignored. If the photocell is occupied after the START input, the photocell will be ignored. If the photocell is occupied during closing, the gate will reopen |  |  |
|  |  | STOP and close | If the photocell is occupied during closing, it stops the gate movement; when released, the closing continues |  |  |
|  |  | Close | The photocell stops the gate until it is occupied in both opening and closing; when released, it send a closing input (the gate closes 1s after the photocell release) |  |  |
|  |  | Pause reload | If the photocell is occupied during opening or closing, it stops the gate movement; when released, the movement continues. If the photocell is occupied during the pause, it recharges the pause time set |  |  |
|  |  | Delete pause time | If the photocell is occupied during opening, pause or closing, the gate reopens completely and closes without observing the pause time set |  |  |



| SPECIAL MENU |  | SET | DESCRIPTION | Default | Note |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 106 | DIAGNOSTICS | 10 | To display the last 10 events (alarms) (See Chapter «ALARMS») | ---- |  |
| 107 | MAINTENANCE CYCLES | 100240000 | Adjustable from 100 to 240000 cycles | 100000 |  |
| 108 | PERFORMED CYCLES | 0240000 | To display the executed cycles. Hold pressed OK to reset the cycles | 0 |  |
| 112 | PASSWORD | Note: «0000» setting is not allowed | To enter a password for blocking the control unit parameters modification | --- |  |
| 114 | EXP MANAGEMENT | SEM 2 | The SEM 2 management unit can be connected to the EXP input | SEM2 |  |
|  |  | Relay | A relay management unit can be connected to the EXP input |  |  |
| 116 | REPEAT LEAF DELAY | On Off | In case of a STOP command when the gate is on its halfway, the leaves will repeat the «leaf delay» set on menus 26-27 | On |  |
| 118 | LATCH | Off | Disabled | Off |  |
|  |  | Opening | To enable the LATCH button wired to the «PARTIAL START» N.O. input; (the PARTIAL START function will be disabled) <br> after a LATCH button command the gate opens and stay open till a new LATCH button command |  |  |
|  |  | Closing | To enable the LATCH button wired to the «PARTIAL START» N.O. input; (the PARTIAL START function will be disabled) <br> after a LATCH button command the gate closes and stay closed till a new LATCH button command |  |  |

To disable the LATCH, press one more time the same button used to enable The LATCH command can also be sent from Tx or SEACLOUD, thus keeping the PARTIAL START input free

| 119 | DISPLAY WRITING <br> SPEED | From $30 \%$ to $100 \%$ | The scrolling speed of the text can be adjusted from <br> to $100 \%$ | $80 \%$ |
| :--- | :--- | :--- | :--- | :--- |

If the menu 119 is set to the minimum value of $30 \%$, the scrolling speed will be low. On the contrary, if adjusted to the maximum value of $100 \%$, the scrolling speed of the text will be very high.
Note: the speed does not change on the display of the JOLLY 3 programmer!

| 120 | BASIC MENU | Press OK to exit the special menu. <br> The special menu switches off automatically after 20 minutes |  |  |
| :---: | :---: | :---: | :---: | :---: |
| 121 | PHOTO 1 TYPE <br> Menu available on model R2BF only | Normal | Standard photocell without 10 K control | Normal |
|  |  | Photo 110 K | Photocell with 10K control |  |
| 122 | PHOTO 2 TYPE <br> Menu available on model R2BF only | Normal | Standard photocell without 10K control | Normal |
|  |  | Photo 2 10K | Photocell with 10K control |  |
| 132 | RELAY <br> Menu available on model R2BF only | START 3s | To enable the Relay for 3 seconds reopening command | Start 3s |
|  |  | Off | Disabled |  |
| 190 | BASIC MENU <br> On model R2BF only | Press OK to exit the special menu. <br> The special menu switches off automatically after 20 minutes |  |  |

## PART FOR BOTH INSTALLER AND END-USER

MAINTENANCE: periodically, it would be advisable to reprogram the working times on the control unit according to the number of cycles performed over time and according to the type of operator, especially if changes in friction, malfunctions or non-compliance with the previously set working times are noticed. Periodically clean the optical system of the photocells.
SAFETY PRECAUTIONS: all electrical works and the choice of the operating logic should comply with the current regulations. A 16A/0,030 differential switch must be used. Separate the source cables (operators, power supply) and command cables (photocells, push-buttons, etc). Be sure the system is properly grounded. Always run cables in separate sheaths to prevent interferences
SPARE PARTS: send request for spare parts to: SEA S.p.A. - Teramo -ITALY - www.seateam.com
SAFETY AND ENVIRONMENTAL COMPATIBILITY: do not waste product packaging materials and/or circuits; do not dispose of the product with other domestic waste at the end of its life cycle. In order to avoid any possible environmental or health damage caused by irregular waste disposal, we recommend to separate this product from other types of waste and to recycle it in a responsible way in order to provide the sustainable re-use of material resources. Domestic users are invited to contact the retailer where the product has been purchased or the local office to get all the information related to differential waste collection and recycling of this kind of product.
STORAGE: $T=-30^{\circ} \mathrm{C} /+60^{\circ} \mathrm{C}$; Humidity $=$ min. $5 \% /$ max. $90 \%$ (without condensation); Materials must be properly packaged, handled with care and with appropriate vehicles
WARRANTY LIMITS: - see the sales conditions
MAINTENANCEAND DECOMMISSION: must be carried out only by specialized and authorized personnel

## THE MANUFACTURER CAN NOT BE DEEMED RESPONSIBLE FOR ANY DAMAGE OR INJURY CAUSED BY IMPROPER USE OF THIS PRODUCT

SEA S.p.A. reserves the right to make any required modification or change to the products and/or to this manual without any advanced notice obligation.

## GENERAL NOTICE

1. Read carefully these instructions before beginning to install the product. Store these instructions for future reference
2. Don'twaste product packaging materials and/or circuits
3. This product was designed and built strictly for the use indicated in this documentation. Any other use, not expressly indicated here, could compromise the good condition/operation of the product and/or be a source of danger. SEA S.p.A. declines all liability caused by improper use or different use in respect to the intended one.
4. The mechanical parts must comply with Directives: Machine Regulation 2006/42/CE and following adjustments, Low Tension (2006/95/CE), Electromagnetic Consistency (2004/108/CE); Installation mustrespect Directives: EN12453 and EN12445.
5. Do not install the equipment in an explosive atmosphere.
6. SEA S.p.A. is not responsible for failure to observe Good Techniques in the construction of the locking elements to motorize or for any deformation that may occur during use
7. Before attempting any job on the system, cut out electrical power and disconnect the batteries. Be sure that the grounding system is perfectly constructed, and connect to it the metal parts of the gate
8. Use of the indicator-light is recommended for every system, as well as a warning sign well-fixed to the frame structure.
9. SEA S.p.A. declines all liability concerning the automated system safety and efficiency, if components used are not produced by SEA
10. For maintenance, strictly use original parts by SEA.
11. Do not modify in any way the components of the automated system.
12. The installer shall supply all information concerning the system manual functioning in case of emergency and shall hand over to the user the warnings handbook supplied with the product.
13. Do not allow children or adults to stay near the product while it is operating. The application cannot be used by children, by people with reduced physical, mental or sensorial capacity or by people without experience or necessary training. Keep remote controls or other pulse generators away from children, to prevent involuntary activation of the system.
14. Transit through the leaves is allowed only when the gate is fully open.
15. The User must not attempt to repair or to take direct action on the system and must solely contact qualified SEA personnel or SEA service centers. The User can apply only the manual function of emergency.
16. The power cables maximum length between the central engine and motors should not be greater than 10 m . Use cables with $2,5 \mathrm{~mm} 2$ section. Use double insulation cable (cable sheath) to the immediate vicinity of the terminals, in particular for the 230 V cable. Keep an adequate distance (at least 2.5 mm in air), between the conductors in low voltage (230V) and the conductors in safety low voltage (SELV) or use an appropriate sheath that provides extra insulation having a thickness of 1 mm

## TERMS OF SALE

EFFICACY OF THE FOLLOWING TERMS OF SALE: the following general terms of sale shall be applied to all orders sent to SEA S.p.A. All sales made by SEA to all customers are made under the prescription of this terms of sales which are integral part of sale contract and cancel and substitute all apposed clauses or specific negotiations present in order document received from the buyer.
GENERAL NOTICE The systems must be assembled exclusively with SEA components, unless specific agreements apply. Non-compliance with the applicable safety standards (European Standards EN12453 - EN 12445) and with good installation practice releases SEA from any responsibilities. SEA shall not be held responsible for any failure to execute a correct and safe installation under the above mentioned standards.

1) PROPOSED ORDER The proposed order shall be accepted only prior SEA approval of it. By signing the proposed order, the Buyer shall be bound to enter a purchase agreement, according to the specifications stated in the proposed order. On the other hand, failure to notify the Buyer of said approval mustnot be construed as automatic acceptance on the part of SEA.
2) PERIOD OF THE OFFER The offer proposed by SEA or by its branch sales department shall be valid for 30 solar days, unless otherwise notified. 3) PRICING The prices in the proposed order are quoted from the Price List which is valid on the date the order was issued. The discounts granted by the branch sales department of SEA shall apply only prior to acceptance on the part of SEA. The prices are for merchandise delivered ex-works from the SEA establishment in Teramo, not including VAT and special packaging. SEA reserves the right to change at any time this price list, providing timely notice to the sales network. The special sales conditions with extra discount on quantity basis ( $\mathrm{Qx}, \mathrm{Qx1}, \mathrm{Qx2}, \mathrm{Qx3}$ formula) is reserved to official distributors under SEA management written agreement.
3) PAYMENTS The accepted forms of payment are each time notified or approved by SEA. The interest rate on delay in payment shall be $1.5 \%$ every month but anyway shall not be higher than the max. interest rate legally permitted.
4) DELIVERY shall take place, approximately and not peremptorily, within 30 working days from the date of receipt of the order, unless otherwise notified. Transport of the goods shall be at Buyer's cost and risk. SEA shall not bear the costs of delivery giving the goods to the carrier, as chosen either by SEA or by the Buyer. Any loss or damage of the goods during transport, are at Buyer's cost
5) COMPLAINTS Any complaints or claims shall be sent to SEA within 8 solar days from receipt of the goods, proved by adequate supporting documents as to their truthfulness
6) SUPPLY The concerning order will be accepted by SEA without any engagement and subordinately to the possibility to get its supplies of raw material which is necessary for the production; Eventual completely or partially unsuccessful executions cannot be reason for complaints or reservations for damage. SEA supply is strictly limited to the goods of its manufacturing, not including assembly, installation and testing. SEA, therefore, disclaims any responsibility for damage deriving, also to third parties, from non-compliance of safety standards and good practice during installation and use of the purchased products.
7) WARRANTY The standard warranty period is 12 months. This warranty time can be extended by means of expedition of the warranty coupon as follows:
SILVER: The mechanical components of the operators belonging to this line are guaranteed for 24 months from the date of manufacturing written on the operator.
GOLD: The mechanical components of the operators belonging to this line are guaranteed for 36 months from the date of manufacturing written on the operator.
PLATINUM: The mechanical components of the operators belonging to this line are guaranteed for 36 months from the date of manufacturing written on the operator. The base warranty ( 36 months) will be extended for further 24 months (up to a total of 60 months) when it is acquired the certificate of warranty which will be filled in and sent to SEAS.p.A. The electronic devices and the systems of command are guaranteed for 24 months from the date of manufacturing. In case of defective product, SEA undertakes to replace free of charge or to repair the goods provided that they are returned to SEA repair centre. The definition of warranty status is by unquestionable assessment of SEA. The replaced parts shall remain propriety of SEA. Binding upon the parties, the material held in warranty by the Buyer, must be sent back to SEA repair centre with fees prepaid, and shall be dispatched by SEA with carriage forward. The warranty shall not cover any required labour activities. The recognized defects, whatever their nature, shall not produce any responsibility and/or damage claim on the part of the Buyer against SEA. The guarantee is in no case recognized if changes are made to the goods, or in the case of improper use, or in the case of tampering or improper assembly, or if the label affixed by the manufacturer has been removed including the SEA registered trademark No. 804888. Furthermore, the warranty shall not apply if SEA products are partly or completely coupled with non-original mechanical and/or electronic components, and in particular, without a specific relevant authorization, and if the Buyer is not making regular payments. The warranty shall not cover damage caused by transport, expendable material, faults due to non-conformity with performance specifications of the products shown in the price list. No indemnification is granted during repairing and/or replacing of the goods in warranty. SEA disclaims any responsibility for damage to objects and persons deriving from non-compliance with safety standards, installation instructions or use of sold goods. The repair of products under warranty and out of warranty is subject to compliance with the procedures notified by SEA
8) RESERVED DOMAIN A clause of reserved domain applies to the sold goods; SEA shall decide autonomously whether to make use of it or not, whereby the Buyer purchases property of the goods only after full payment of the latter.
9) COMPETENT COURT OF LAW In case of disputes arising from the application of the agreement, the competent court of law is the tribunal of Teramo. SEA reserves the faculty to make technical changes to improve its own products, which are not in this price list at any moment and without notice. SEA declines any responsibility due to possible mistakes contained inside the present price list caused by printing and/or copying. The present price list cancels and substitutes the previous ones. The Buyer, according to the Law No. 196/2003 (privacy code) consents to put his personal data, deriving from the present contract, in SEA archives and electronic files, and he also gives his consent to their treatment for commercial and administrative purposes.
Industrial ownership rights: once the Buyer has recognized that SEA has the exclusive legal ownership of the registered SEA brand num. 804888 affixed on product labels and/or on manuals and/or on any other documentation, he will commit himself to use it in a way which does not reduce the value of these rights, he won't also remove, replace or modify brands or any other particularity from the products. Any kind of replication or use of SEA brand is forbidden as well as of any particularity on the products, unless preventive and expressed authorization by SEA. In accomplishment with art. 1341 of the Italian Civil Law it will be approved expressively clauses under numbers: 4) PAYMENTS -8) GUARANTEE - 10) COMPETENT COURT OF LAW

Altornatic Gate Dpeners

## DECLARATION OF CONFORMITY DICHIARAZIONE DI CONFORMITÀ

SA S.p.A. declares under its proper responsibility and, if applicable, under the responsibility of its authorised representative that, by installing the appropriate safety equipment and noise filtering, the products:
La SEA S.p.A. dichiara sotto la propria responsabilità e, se applicabile, del suo rappresentante autorizzato che, con l'installazione degli adeguati dispositivi di sicurezza e di filtraggio disturbi, iprodotti:

Description - Descrizione

SWING 2 DG R2F
(AND ALL ITS Br-PRODUCTS - E TUTTI I SUOI DERIVATI)

Model - Modello

23021096

Trademark - Marca

SEA

- are built to be integrated into a machine or to be assembled with other machinery to create a machine under the provisions of Directive 2006/42/CE;
- comply with the essential safety requirements related to the products within the field of applicability of the Community Directives 2014/35/UE and 2014/30/UE
- sono costruiti per essere incorporati in una macchina o per essere assemblati con altri macchinari per costruire una macchina a i sensi della Direttiva 2006/42/CE;
- sono conformi ai requisiti essenziali di sicurezza relativi ai prodotti entro il campo di applicabilità delle Direttive Comunitarie 2014/35/UE e 2014/30/UE

Place and Date of Issue
Luogo e Data di Emissione
Teramo, 06/09/2029



## Automatic Gate Dpeners

International registered trademark n. 804888

## SEA S.p.A.

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[^0]:    * All the 24 V outputs support a maximum load of 500 mA - referred to the sum of the loads of all 24 V accessories connected, including the absorption of the receiver on board ( 30 mA
    ** The special CN6 connector is build only on the model SWING 2 DG R2F «FC» with limit switch management *** The dry contact CN8 connector supports a maximum load of 3 A and 250 V ; it is available only on the R2 DRY CONTACT hardware version with additional relay

[^1]:    * While the partial impulses are displayed, it is possible to OPEN (by pressing UP) or CLOSE (by pressing DOWN) the operator to verify the correct reading of the potentiometer - only for «POSITION GATE»

